

## FEATURES

**Wide bandwidth: 1 MHz to 10 GHz**  
**High accuracy:  $\pm 1.0$  dB over temperature**  
**55 dB dynamic range up to 8 GHz  $\pm 3$  dB error**  
**Stability over temperature:  $\pm 0.5$  dB**  
**Low noise measurement/controller output, VOUT**  
**Pulse response time: 6 ns/10 ns (fall/rise)**  
**Small footprint, 2 mm  $\times$  3 mm LFCSP**  
**Supply operation: 3.0 V to 5.5 V at 22 mA**  
**Fabricated using high speed SiGe process**

## APPLICATIONS

**RF transmitter PA setpoint control and level monitoring**  
**Power monitoring in radio link transmitters**  
**RSSI measurement in base stations, WLANs, WiMAX, and radars**

## GENERAL DESCRIPTION

The **AD8317** is a demodulating logarithmic amplifier, capable of accurately converting an RF input signal to a corresponding decibel-scaled output. It employs the progressive compression technique over a cascaded amplifier chain, each stage of which is equipped with a detector cell. The device can be used in either measurement or controller modes. The **AD8317** maintains accurate log conformance for signals of 1 MHz to 8 GHz and provides useful operation to 10 GHz. The input dynamic range is typically 55 dB (referenced to 50  $\Omega$ ) with less than  $\pm 3$  dB error. The **AD8317** has 6 ns/10 ns response time (fall time/rise time) that enables RF burst detection to a pulse rate of beyond 50 MHz. The device provides unprecedented logarithmic intercept stability vs. ambient temperature conditions. A supply of 3.0 V to 5.5 V is required to power the device. Current consumption is typically 22 mA, and it decreases to 200  $\mu$ A when the device is disabled.

The **AD8317** can be configured to provide a control voltage to a power amplifier or a measurement output from the VOUT pin. Because the output can be used for controller applications, special attention has been paid to minimize wideband noise. In this mode, the setpoint control voltage is applied to the VSET pin.

## FUNCTIONAL BLOCK DIAGRAM

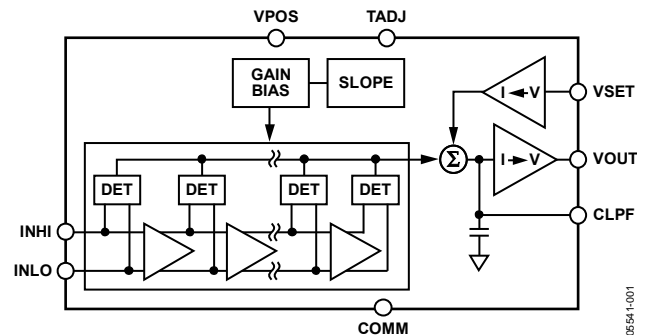


Figure 1.

The feedback loop through an RF amplifier is closed via VOUT, the output of which regulates the output of the amplifier to a magnitude corresponding to  $V_{SET}$ . The **AD8317** provides 0 V to ( $V_{POS} - 0.1$  V) output capability at the VOUT pin, suitable for controller applications. As a measurement device, VOUT is externally connected to VSET to produce an output voltage,  $V_{OUT}$ , that is a decreasing linear-in-dB function of the RF input signal amplitude.

The logarithmic slope is  $-22$  mV/dB, determined by the VSET interface. The intercept is 15 dBm (referenced to 50  $\Omega$ , CW input) using the INHI input. These parameters are very stable against supply and temperature variations.

The **AD8317** is fabricated on a SiGe bipolar IC process and is available in a 2 mm  $\times$  3 mm, 8-lead LFCSP with an operating temperature range of  $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$ .

## TABLE OF CONTENTS

Features .....	1	Input Signal Coupling.....	11
Applications.....	1	Output Interface .....	11
Functional Block Diagram .....	1	Setpoint Interface .....	11
General Description .....	1	Temperature Compensation of Output Voltage.....	12
Revision History .....	2	Measurement Mode .....	12
Specifications.....	3	Setting the Output Slope in Measurement Mode .....	13
Absolute Maximum Ratings.....	5	Controller Mode.....	13
ESD Caution.....	5	Output Filtering.....	15
Pin Configuration and Function Descriptions.....	6	Operation Beyond 8 GHz .....	15
Typical Performance Characteristics .....	7	Evaluation Board .....	16
Theory of Operation .....	10	Die Information.....	18
Using the AD8317 .....	11	Outline Dimensions .....	19
Basic Connections .....	11	Ordering Guide .....	19

## REVISION HISTORY

### 8/2017—Rev. B to Rev. C

Change to Figure 2 and Table 3 .....	6
Updated Outline Dimensions.....	19
Changes to Ordering Guide .....	19

### 3/2008—Rev. A to Rev. B

Changes to Features.....	1
Changes to General Description .....	1
Changes to Measurement Mode Section.....	12
Changes to Equation 12 .....	15

### 8/2007—Rev. 0 to Rev. A

Changes to $f = 8.0$ GHz, $\pm 1$ dB Dynamic Range Parameter.....	4
Changes to Table 2.....	6
Changes to Figure 20.....	10
Changes to Setpoint Interface Section and Figure 22.....	12
Changes Figure 27 .....	13
Changes to Table 5.....	17
Added Die Information Section .....	19
Changes to Ordering Guide .....	21

### 10/2005—Revision 0: Initial Version

## SPECIFICATIONS

$V_{POS} = 3\text{ V}$ ,  $C_{LFP} = 1000\text{ pF}$ ,  $T_A = 25^\circ\text{C}$ ,  $52.3\ \Omega$  termination resistor at INHI, unless otherwise noted.

**Table 1.**

Parameter	Conditions	Min	Typ	Max	Unit
<b>SIGNAL INPUT INTERFACE</b>					
Specified Frequency Range	INHI (Pin 1)	0.001		10	GHz
DC Common-Mode Voltage			$V_{POS} - 0.6$		V
<b>MEASUREMENT MODE</b>					
VOUT (Pin 5) shorted to VSET (Pin 4), sinusoidal input signal					
$R_{TADJ} = 18\text{ k}\Omega$					
f = 900 MHz					
Input Impedance			1500  0.33		$\Omega$   pF
$\pm 1\text{ dB}$ Dynamic Range	$T_A = 25^\circ\text{C}$		50		dB
	$-40^\circ\text{C} < T_A < +85^\circ\text{C}$		46		dB
Maximum Input Level	$\pm 1\text{ dB}$ error		-3		dBm
Minimum Input Level	$\pm 1\text{ dB}$ error		-53		dBm
Slope <sup>1</sup>		-25	-22	-19.5	mV/dB
Intercept <sup>1</sup>		12	15	21	dBm
Output Voltage, High Power In	$P_{IN} = -10\text{ dBm}$	0.42	0.58	0.78	V
Output Voltage, Low Power In	$P_{IN} = -40\text{ dBm}$	1.00	1.27	1.40	V
f = 1.9 GHz	$R_{TADJ} = 8\text{ k}\Omega$				
Input Impedance			950  0.38		$\Omega$   pF
$\pm 1\text{ dB}$ Dynamic Range	$T_A = 25^\circ\text{C}$		50		dB
	$-40^\circ\text{C} < T_A < +85^\circ\text{C}$		48		dB
Maximum Input Level	$\pm 1\text{ dB}$ error		-4.00		dBm
Minimum Input Level	$\pm 1\text{ dB}$ error		-54		dBm
Slope <sup>1</sup>		-25	-22	-19.5	mV/dB
Intercept <sup>1</sup>		10	14	20	dBm
Output Voltage, High Power In	$P_{IN} = -10\text{ dBm}$	0.35	0.54	0.80	V
Output Voltage, Low Power In	$P_{IN} = -35\text{ dBm}$	0.75	1.21	1.35	V
f = 2.2 GHz	$R_{TADJ} = 8\text{ k}\Omega$				
Input Impedance			810  0.39		$\Omega$   pF
$\pm 1\text{ dB}$ Dynamic Range	$T_A = 25^\circ\text{C}$		50		dB
	$-40^\circ\text{C} < T_A < +85^\circ\text{C}$		47		dB
Maximum Input Level	$\pm 1\text{ dB}$ error		-5		dBm
Minimum Input Level	$\pm 1\text{ dB}$ error		-55		dBm
Slope <sup>1</sup>			-22		mV/dB
Intercept <sup>1</sup>			14		dBm
Output Voltage, High Power In	$P_{IN} = -10\text{ dBm}$		0.53		V
Output Voltage, Low Power In	$P_{IN} = -40\text{ dBm}$		1.20		V
f = 3.6 GHz	$R_{TADJ} = 8\text{ k}\Omega$				
Input Impedance			300  0.33		$\Omega$   pF
$\pm 1\text{ dB}$ Dynamic Range	$T_A = 25^\circ\text{C}$		42		dB
	$-40^\circ\text{C} < T_A < +85^\circ\text{C}$		40		dB
Maximum Input Level	$\pm 1\text{ dB}$ error		-6		dBm
Minimum Input Level	$\pm 1\text{ dB}$ error		-48		dBm
Slope <sup>1</sup>			-22		mV/dB
Intercept <sup>1</sup>			11		dBm
Output Voltage, High Power In	$P_{IN} = -10\text{ dBm}$		0.47		V
Output Voltage, Low Power In	$P_{IN} = -40\text{ dBm}$		1.16		V

Parameter	Conditions	Min	Typ	Max	Unit
f = 5.8 GHz	$R_{TADJ} = 500 \Omega$				
Input Impedance			110  0.05		$\Omega$   pF
±1 dB Dynamic Range	$T_A = 25^\circ\text{C}$		50		dB
	$-40^\circ\text{C} < T_A < +85^\circ\text{C}$		48		dB
Maximum Input Level	±1 dB error		-4		dBm
Minimum Input Level	±1 dB error		-54		dBm
Slope <sup>1</sup>			-22		mV/dB
Intercept <sup>1</sup>			16		dBm
Output Voltage, High Power In	$P_{IN} = -10 \text{ dBm}$		0.59		V
Output Voltage, Low Power In	$P_{IN} = -40 \text{ dBm}$		1.27		V
f = 8.0 GHz	$R_{TADJ} = \text{open}$				
Input Impedance			28  0.79		$\Omega$   pF
±1 dB Dynamic Range	$T_A = 25^\circ\text{C}$		44		dB
	$-40^\circ\text{C} < T_A < +85^\circ\text{C}$		35		dB
Maximum Input Level	±1 dB error		-2		dBm
Minimum Input Level	±1 dB error		-46		dBm
Slope <sup>2</sup>			-22		mV/dB
Intercept <sup>2</sup>			21		dBm
Output Voltage, High Power In	$P_{IN} = -10 \text{ dBm}$		0.70		V
Output Voltage, Low Power In	$P_{IN} = -40 \text{ dBm}$		1.39		V
<b>OUTPUT INTERFACE</b>	<b>VOUT (Pin 5)</b>				
Voltage Swing	$V_{SET} = 0 \text{ V}, R_{FIN} = \text{open}$		$V_{POS} - 0.1$		V
	$V_{SET} = 1.7 \text{ V}, R_{FIN} = \text{open}$		10		mV
Output Current Drive	$V_{SET} = 0 \text{ V}, R_{FIN} = \text{open}$		10		mA
Small Signal Bandwidth	$R_{FIN} = -10 \text{ dBm}$ , from CLPF to VOUT		140		MHz
Output Noise	$R_{FIN} = 2.2 \text{ GHz}$ , $-10 \text{ dBm}$ , $f_{NOISE} = 100 \text{ kHz}$ , $C_{LPF} = \text{open}$		90		nV/ $\sqrt{\text{Hz}}$
Fall Time	Input level = no signal to $-10 \text{ dBm}$ , 90% to 10%, $C_{LPF} = 8 \text{ pF}$		18		ns
	Input level = no signal to $-10 \text{ dBm}$ , 90% to 10%, $C_{LPF} = \text{open}$ , $R_{OUT} = 150 \Omega$		6		ns
Rise Time	Input level = $-10 \text{ dBm}$ to no signal, 10% to 90%, $C_{LPF} = 8 \text{ pF}$		20		ns
	Input level = $-10 \text{ dBm}$ to no signal, 10% to 90%, $C_{LPF} = \text{open}$ , $R_{OUT} = 150 \Omega$		10		ns
Video Bandwidth (or Envelope Bandwidth)			50		MHz
<b>VSET INTERFACE</b>	<b>VSET (Pin 4)</b>				
Nominal Input Range	$R_{FIN} = 0 \text{ dBm}$ , measurement mode		0.35		V
	$R_{FIN} = -50 \text{ dBm}$ , measurement mode		1.40		V
Logarithmic Scale Factor			-45		dB/V
Input Resistance	$R_{FIN} = -20 \text{ dBm}$ , controller mode, $V_{SET} = 1 \text{ V}$		40		k $\Omega$
<b>TADJ INTERFACE</b>	<b>TADJ (Pin 6)</b>				
Input Resistance	$TADJ = 0.9 \text{ V}$ , sourcing $50 \mu\text{A}$		13		k $\Omega$
Disable Threshold Voltage	$TADJ = \text{open}$		$V_{POS} - 0.4$		V
<b>POWER INTERFACE</b>	<b>VPOS (Pin 7)</b>				
Supply Voltage		3.0		5.5	V
Quiescent Current		18	22	30	mA
vs. Temperature	$-40^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$		60		$\mu\text{A}/^\circ\text{C}$
Disable Current	$TADJ = V_{POS}$		200		$\mu\text{A}$

<sup>1</sup> Slope and intercept are determined by calculating the best-fit line between the power levels of  $-40 \text{ dBm}$  and  $-10 \text{ dBm}$  at the specified input frequency.

<sup>2</sup> Slope and intercept are determined by calculating the best-fit line between the power levels of  $-34 \text{ dBm}$  and  $-16 \text{ dBm}$  at  $8.0 \text{ GHz}$ .

## ABSOLUTE MAXIMUM RATINGS

Table 2.

Parameter	Rating
Supply Voltage, $V_{POS}$	5.7 V
$V_{SET}$ Voltage	0 V to $V_{POS}$
Input Power (Single-Ended, Referenced to 50 $\Omega$ )	12 dBm
Internal Power Dissipation	0.73 W
$\theta_{JA}$	55°C/W
Maximum Junction Temperature	125°C
Operating Temperature Range	-40°C to +85°C
Storage Temperature Range	-65°C to +150°C
Lead Temperature (Soldering, 60 sec)	260°C

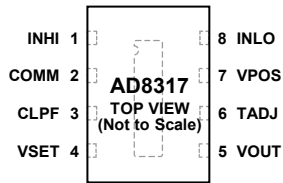
Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

### ESD CAUTION



**ESD (electrostatic discharge) sensitive device.** Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS



NOTES  
1. EXPOSED PAD MUST BE CONNECTED TO GROUND VIA A LOW IMPEDANCE PATH.

05841-002

Figure 2. Pin Configuration

Table 3. Pin Function Descriptions

Pin No.	Mnemonic	Description
1	INHI	RF Input. Nominal input range of $-50$ dBm to $0$ dBm, referenced to $50 \Omega$ ; ac-coupled RF input.
2	COMM	Device Common. Connect to a low impedance ground plane.
3	CLPF	Loop Filter Capacitor. In measurement mode, this capacitor sets the pulse response time and video bandwidth. In controller mode, the capacitance on this node sets the response time of the error amplifier/integrator.
4	VSET	Setpoint Control Input for Controller Mode or Feedback Input for Measurement Mode.
5	VOUT	Measurement and Controller Output. In measurement mode, VOUT provides a decreasing linear-in-dB representation of the RF input signal amplitude. In controller mode, VOUT is used to control the gain of a VGA or VVA with a positive gain sense (increasing voltage increases gain).
6	TADJ	Temperature Compensation Adjustment. Frequency-dependent temperature compensation is set by connecting a ground-referenced resistor to this pin.
7	VPOS	Positive Supply Voltage: $3.0$ V to $5.5$ V.
8	INLO	RF Common for INHI. AC-coupled RF common.
	EPAD	Exposed Pad. Exposed pad must be connected to ground via a low impedance path.

### TYPICAL PERFORMANCE CHARACTERISTICS

$V_{POS} = 3\text{ V}$ ;  $T_A = +25^\circ\text{C}, -40^\circ\text{C}, +85^\circ\text{C}$ ;  $C_{LPF} = 1000\text{ pF}$ , unless otherwise noted. Black:  $+25^\circ\text{C}$ ; Blue:  $-40^\circ\text{C}$ ; Red:  $+85^\circ\text{C}$ . Error is calculated by using the best-fit line between  $P_{IN} = -40\text{ dBm}$  and  $P_{IN} = -10\text{ dBm}$  at the specified input frequency, unless otherwise noted

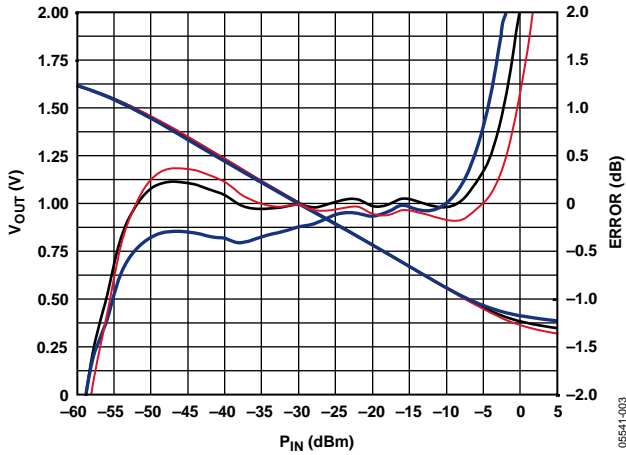


Figure 3.  $V_{OUT}$  and Log Conformance vs. Input Amplitude at 900 MHz,  $R_{TADJ} = 18\text{ k}\Omega$

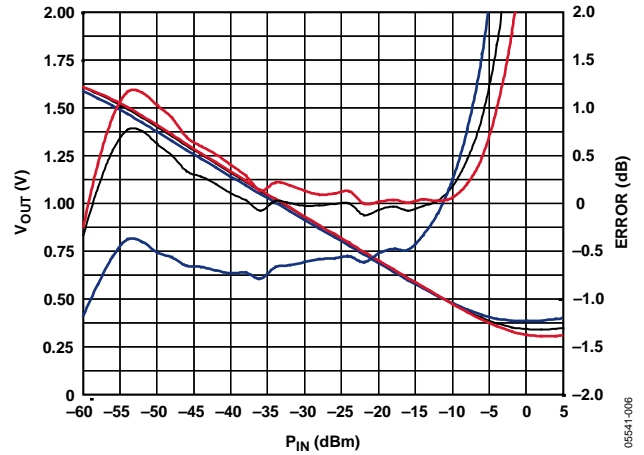


Figure 6.  $V_{OUT}$  and Log Conformance vs. Input Amplitude at 3.6 GHz,  $R_{TADJ} = 8\text{ k}\Omega$

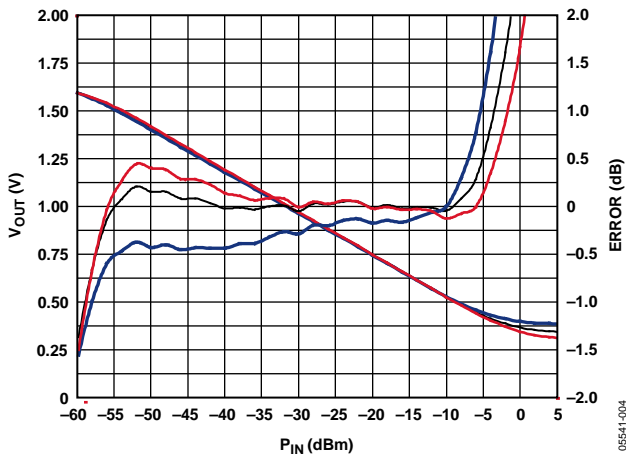


Figure 4.  $V_{OUT}$  and Log Conformance vs. Input Amplitude at 1.9 GHz,  $R_{TADJ} = 8\text{ k}\Omega$

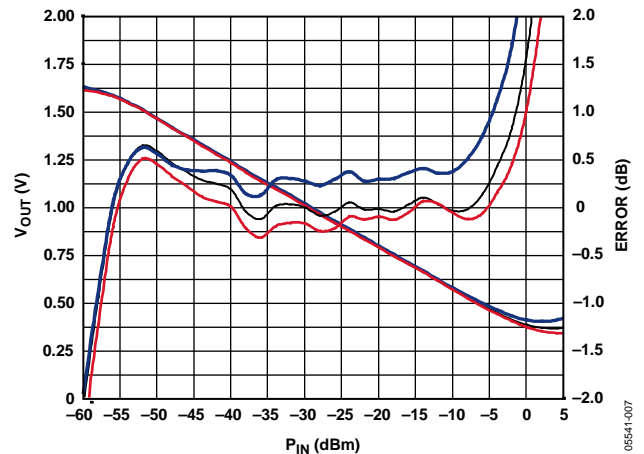


Figure 7.  $V_{OUT}$  and Log Conformance vs. Input Amplitude at 5.8 GHz,  $R_{TADJ} = 500\ \Omega$

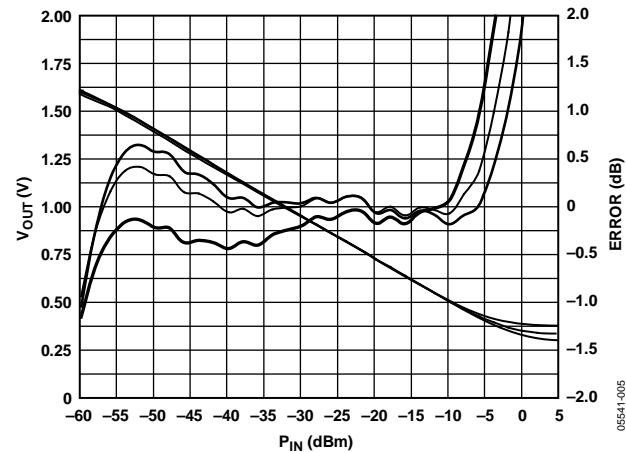


Figure 5.  $V_{OUT}$  and Log Conformance vs. Input Amplitude at 2.2 GHz,  $R_{TADJ} = 8\text{ k}\Omega$

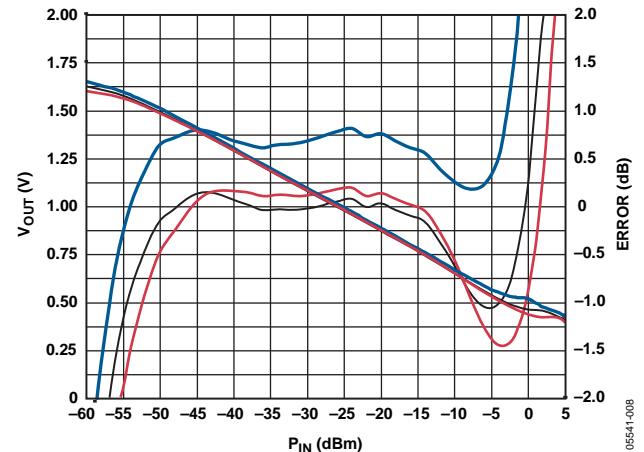


Figure 8.  $V_{OUT}$  and Log Conformance vs. Input Amplitude at 8.0 GHz,  $R_{TADJ} = \text{Open}$ , Error Calculated from  $P_{IN} = -34\text{ dBm}$  to  $P_{IN} = -16\text{ dBm}$

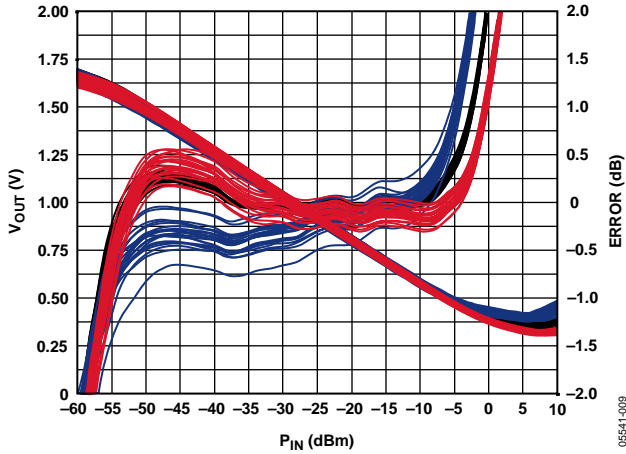


Figure 9.  $V_{OUT}$  and Log Conformance vs. Input Amplitude at 900 MHz, Multiple Devices,  $R_{TADJ} = 18\text{ k}\Omega$

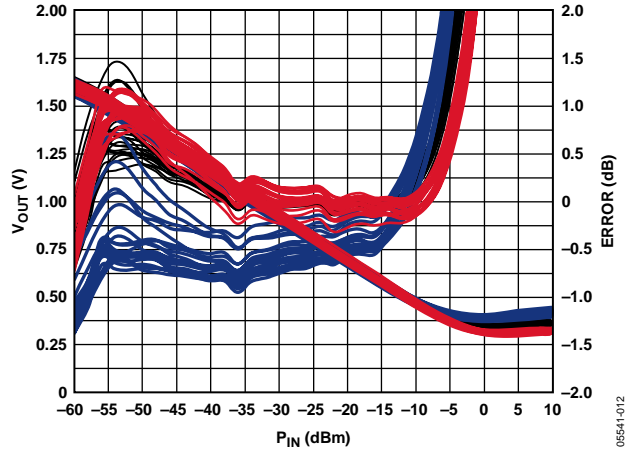


Figure 12.  $V_{OUT}$  and Log Conformance vs. Input Amplitude at 3.6 GHz, Multiple Devices,  $R_{TADJ} = 8\text{ k}\Omega$

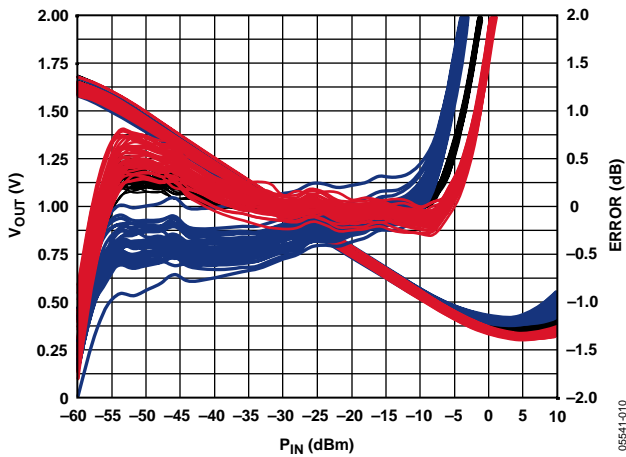


Figure 10.  $V_{OUT}$  and Log Conformance vs. Input Amplitude at 1.9 GHz, Multiple Devices,  $R_{TADJ} = 8\text{ k}\Omega$

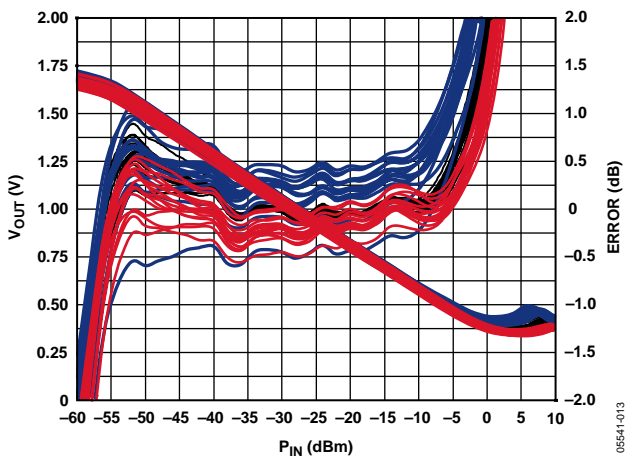


Figure 13.  $V_{OUT}$  and Log Conformance vs. Input Amplitude at 5.8 GHz, Multiple Devices,  $R_{TADJ} = 500\text{ }\Omega$

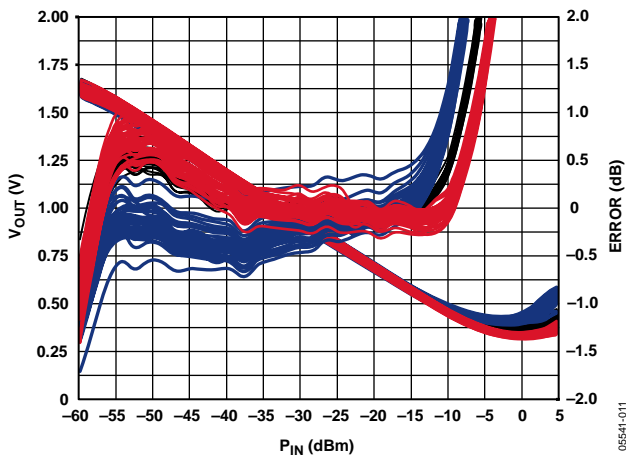


Figure 11.  $V_{OUT}$  and Log Conformance vs. Input Amplitude at 2.2 GHz, Multiple Devices,  $R_{TADJ} = 8\text{ k}\Omega$

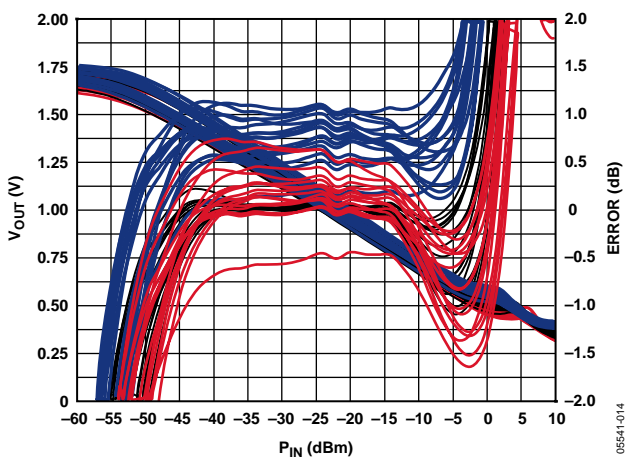


Figure 14.  $V_{OUT}$  and Log Conformance vs. Input Amplitude at 8.0 GHz, Multiple Devices,  $R_{TADJ} = \text{Open}$ , Error Calculated from  $P_{IN} = -34\text{ dBm}$  to  $P_{IN} = -16\text{ dBm}$



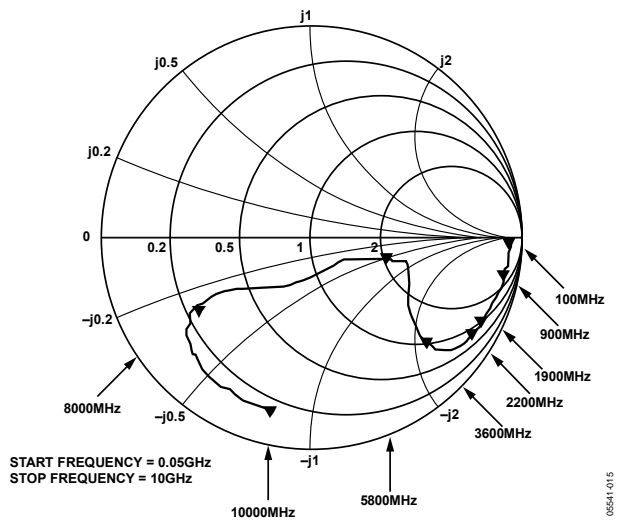


Figure 15. Input Impedance vs. Frequency; No Termination Resistor on INHI (Impedance De-Embedded to Input Pins),  $Z_0 = 50 \Omega$

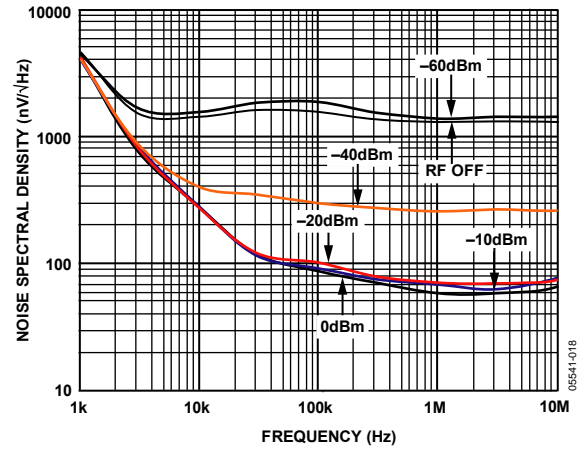


Figure 18. Noise Spectral Density of Output;  $C_{LPF} = \text{Open}$

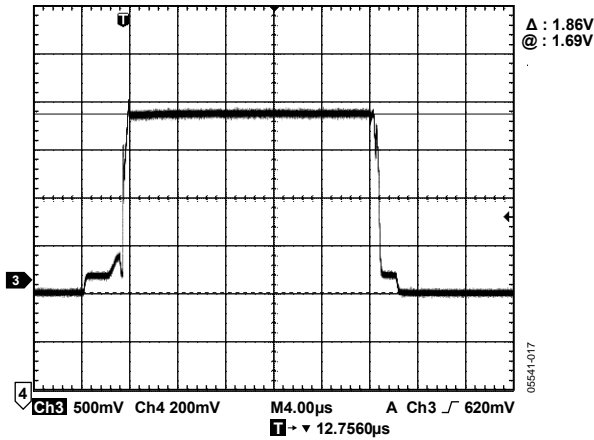


Figure 16. Power-On/Power-Off Response Time;  $V_{POS} = 3.0 \text{ V}$ ; Input AC-Coupling Capacitors =  $10 \text{ pF}$ ;  $C_{LPF} = \text{Open}$

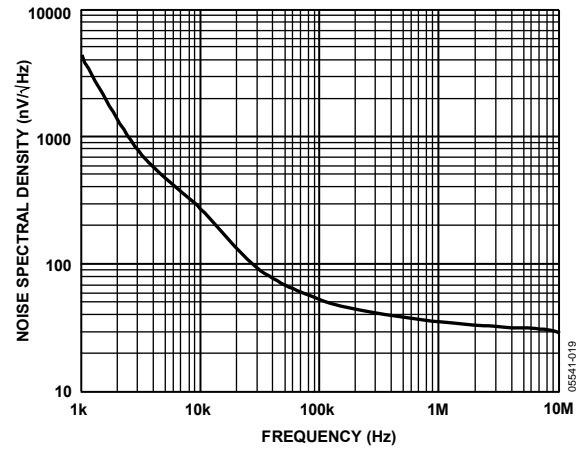


Figure 19. Noise Spectral Density of Output Buffer (from CLPF to VOUT);  $C_{LPF} = 0.1 \mu\text{F}$

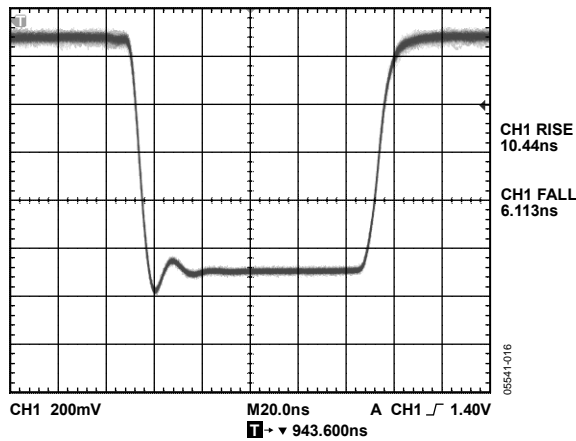


Figure 17.  $V_{OUT}$  Pulse Response Time; Pulsed RF Input  $0.1 \text{ GHz}$ ,  $-10 \text{ dBm}$ ;  $C_{LPF} = \text{Open}$ ;  $R_{LOAD} = 150 \Omega$

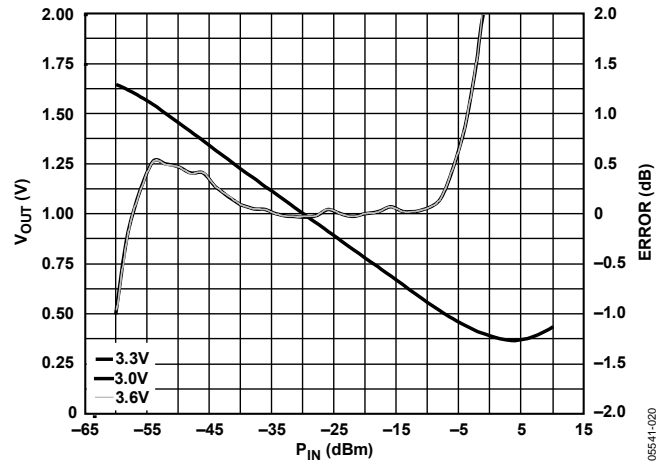


Figure 20. Output Voltage Stability vs. Supply Voltage at  $1.9 \text{ GHz}$  When  $V_{POS}$  Varies by 10%





The slope is given by

$$-I_D \times 2x \times 1.5 \text{ k}\Omega = -22 \text{ mV/dB} \times x$$

For example, if a resistor divider to ground is used to generate a  $V_{SET}$  voltage of  $V_{OUT}/2$ ,  $x = 2$ . The slope is set to  $-880 \text{ V/decade}$  or  $-44 \text{ mV/dB}$ .

## TEMPERATURE COMPENSATION OF OUTPUT VOLTAGE

The primary component of the variation in  $V_{OUT}$  vs. temperature, as the input signal amplitude is held constant, is the drift of the intercept. This drift is also a weak function of the input signal frequency; therefore, provision is made for the optimization of internal temperature compensation at a given frequency by providing Pin TADJ.

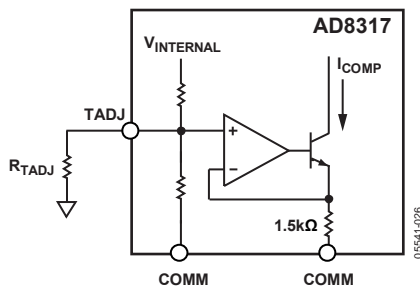


Figure 26. TADJ Interface

$R_{TADJ}$  is connected between TADJ and ground. The value of this resistor partially determines the magnitude of an analog correction coefficient, which is used to reduce intercept drift.

The relationship between output temperature drift and frequency is not linear and cannot be easily modeled. As a result, experimentation is required to choose the correct TADJ resistor. Table 4 shows the recommended values for some commonly used frequencies.

Table 4. Recommended  $R_{TADJ}$  Values

Frequency	Recommended $R_{TADJ}$
50 MHz	18 k $\Omega$
100 MHz	18 k $\Omega$
900 MHz	18 k $\Omega$
1.8 GHz	8 k $\Omega$
1.9 GHz	8 k $\Omega$
2.2 GHz	8 k $\Omega$
3.6 GHz	8 k $\Omega$
5.3 GHz	500 $\Omega$
5.8 GHz	500 $\Omega$
8 GHz	Open

## MEASUREMENT MODE

When the  $V_{OUT}$  voltage or a portion of the  $V_{OUT}$  voltage is fed back to the VSET pin, the device operates in measurement mode. As seen in Figure 27, the AD8317 has an offset voltage, a negative slope, and a  $V_{OUT}$  measurement intercept at the high end of its input signal range.

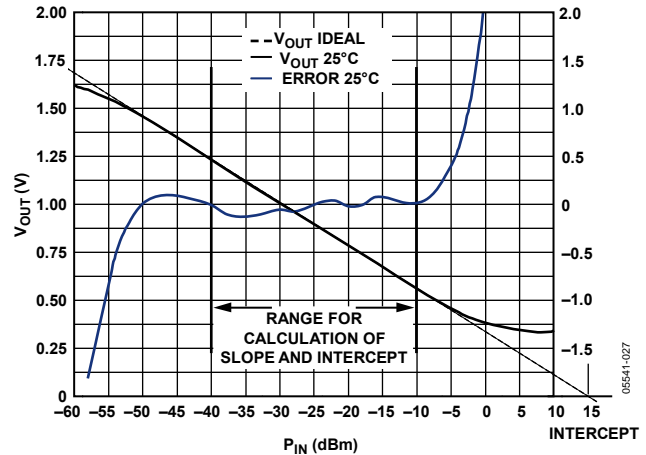


Figure 27. Typical Output Voltage vs. Input Signal

The output voltage vs. input signal voltage of the AD8317 is linear-in-dB over a multidecade range. The equation for this function is

$$V_{OUT} = X \times V_{SLOPE/DEC} \times \log_{10}(V_{IN}/V_{INTERCEPT}) \quad (3)$$

$$= X \times V_{SLOPE/DB} \times 20 \times \log_{10}(V_{IN}/V_{INTERCEPT}) \quad (4)$$

where:

$X$  is the feedback factor in  $V_{SET} = V_{OUT}/X$ .

$V_{SLOPE/DEC}$  is nominally  $-440 \text{ mV/decade}$ , or  $-22 \text{ mV/dB}$ .

$V_{INTERCEPT}$  is the x-axis intercept of the linear-in-dB portion of the  $V_{OUT}$  vs.  $P_{IN}$  curve (see Figure 27).

$V_{INTERCEPT}$  is 2 dBV for a sinusoidal input signal.

An offset voltage,  $V_{OFFSET}$ , of 0.35 V is internally added to the detector signal, so that the minimum value for  $V_{OUT}$  is  $X \times V_{OFFSET}$ ; therefore, for  $X = 1$ , the minimum  $V_{OUT}$  is 0.35 V.

The slope is very stable vs. process and temperature variation. When base-10 logarithms are used,  $V_{SLOPE/DECADE}$  represents the volts/decade. A decade corresponds to 20 dB;  $V_{SLOPE/DECADE}/20 = V_{SLOPE/DB}$  represents the slope in volts/dB.

As noted in Equation 3 and Equation 4, the  $V_{OUT}$  voltage has a negative slope. This is also the correct slope polarity to control the gain of many power amplifiers in a negative feedback configuration. Because both the slope and intercept vary slightly with frequency, it is recommended to refer to the Specifications section for application-specific values for slope and intercept.

Although demodulating log amps respond to input signal voltage, not input signal power, it is customary to discuss the amplitude of high frequency signals in terms of power. In this case, the characteristic impedance of the system,  $Z_0$ , must be known to convert voltages to their corresponding power levels. The following equations are used to perform this conversion:

$$P \text{ [dBm]} = 10 \times \log_{10}(V_{RMS}^2/(Z_0 \times 1 \text{ mW})) \quad (5)$$

$$P \text{ [dBV]} = 20 \times \log_{10}(V_{RMS}/1 \text{ V}_{RMS}) \quad (6)$$

$$P \text{ [dBm]} = P \text{ [dBV]} - 10 \times \log_{10}(Z_0 \times 1 \text{ mW}/1 \text{ V}_{RMS}^2) \quad (7)$$

For example,  $P_{\text{INTERCEPT}}$  for a sinusoidal input signal expressed in terms of dBm (decibels referred to 1 mW), in a 50  $\Omega$  system is

$$\begin{aligned} P_{\text{INTERCEPT}} [\text{dBm}] &= \\ P_{\text{INTERCEPT}} [\text{dBV}] - 10 \times \log_{10}(Z_0 \times 1 \text{ mW}/1 \text{ V}_{\text{RMS}}^2) &= \\ 2 \text{ dBV} - 10 \times \log_{10}(50 \times 10^{-3}) &= 15 \text{ dBm} \end{aligned} \quad (8)$$

For a square wave input signal in a 200  $\Omega$  system,

$$\begin{aligned} P_{\text{INTERCEPT}} &= \\ -1 \text{ dBV} - 10 \times \log_{10}[(200 \Omega \times 1 \text{ mW}/1 \text{ V}_{\text{RMS}}^2)] &= 6 \text{ dBm} \end{aligned}$$

Further information on the intercept variation dependence upon waveform can be found in the [AD8313](#) and [AD8307](#) data sheets.

## SETTING THE OUTPUT SLOPE IN MEASUREMENT MODE

To operate in measurement mode,  $V_{\text{OUT}}$  must be connected to  $V_{\text{SET}}$ . Connecting  $V_{\text{OUT}}$  directly to  $V_{\text{SET}}$  yields the nominal logarithmic slope of approximately  $-22 \text{ mV/dB}$ . The output swing corresponding to the specified input range is then approximately 0.35 V to 1.7 V. The slope and output swing can be increased by placing a resistor divider between  $V_{\text{OUT}}$  and  $V_{\text{SET}}$  (that is, one resistor from  $V_{\text{OUT}}$  to  $V_{\text{SET}}$  and one resistor from  $V_{\text{SET}}$  to ground). The input impedance of  $V_{\text{SET}}$  is approximately 40 k $\Omega$ . To prevent this input impedance from affecting the resulting slope, keep slope-setting resistors below 20 k $\Omega$ . If two equal resistors are used (for example, 10 k $\Omega$ /10 k $\Omega$ ), the slope doubles to approximately  $-44 \text{ mV/dB}$ .

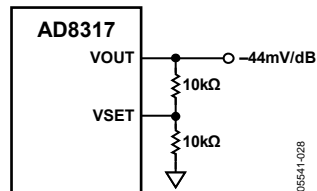


Figure 28. Increasing the Slope

## CONTROLLER MODE

The [AD8317](#) provides a controller mode feature at the  $V_{\text{OUT}}$  pin. By using  $V_{\text{SET}}$  for the setpoint voltage, it is possible for the [AD8317](#) to control subsystems, such as power amplifiers (PAs), variable gain amplifiers (VGAs), or variable voltage attenuators (VVAs), that have output power that increases monotonically with respect to their gain control signal.

To operate in controller mode, the link between  $V_{\text{SET}}$  and  $V_{\text{OUT}}$  is broken. A setpoint voltage is applied to the  $V_{\text{SET}}$  input,  $V_{\text{OUT}}$  is connected to the gain control terminal of the VGA, and the RF input of the detector is connected to the output of the VGA (usually using a directional coupler and some additional attenuation). Based on the defined relationship

between  $V_{\text{OUT}}$  and the RF input signal when the device is in measurement mode, the [AD8317](#) adjusts the voltage on  $V_{\text{OUT}}$  ( $V_{\text{OUT}}$  is now an error amplifier output) until the level at the RF input corresponds to the applied  $V_{\text{SET}}$ . When the [AD8317](#) operates in controller mode, there is no defined relationship between the  $V_{\text{SET}}$  and the  $V_{\text{OUT}}$  voltage;  $V_{\text{OUT}}$  settles to a value that results in the correct input signal level appearing at  $\text{INHI}/\text{INLO}$ .

For this output power control loop to be stable, a ground-referenced capacitor must be connected to the  $\text{CLPF}$  pin. This capacitor,  $C_{\text{FLT}}$ , integrates the error signal (in the form of a current) to set the loop bandwidth and ensure loop stability. Further details on control loop dynamics can be found in the [AD8315](#) data sheet.

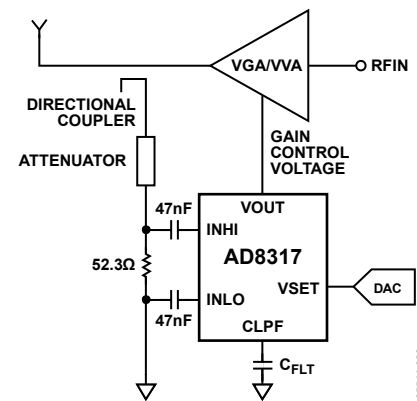


Figure 29. Controller Mode

Decreasing  $V_{\text{SET}}$ , which corresponds to demanding a higher signal from the VGA, increases  $V_{\text{OUT}}$ . The gain control voltage of the VGA must have a positive sense. A positive control voltage to the VGA increases the gain of the device.

The basic connections for operating the [AD8317](#) in an automatic gain control (AGC) loop with the [ADL5330](#) are shown in Figure 30. The [ADL5330](#) is a 10 MHz to 3 GHz VGA. It offers a large gain control range of 60 dB with  $\pm 0.5 \text{ dB}$  gain stability. This configuration is similar to Figure 29.

The gain of the [ADL5330](#) is controlled by the output pin of the [AD8317](#). This voltage,  $V_{\text{OUT}}$ , has a range of 0 V to near  $V_{\text{POS}}$ . To avoid overdrive recovery issues, the [AD8317](#) output voltage can be scaled down using a resistive divider to interface with the 0 V to 1.4 V gain control range of the [ADL5330](#).

A coupler/attenuation of 21 dB is used to match the desired maximum output power from the VGA to the top end of the linear operating range of the [AD8317](#) (approximately  $-5 \text{ dBm}$  at 900 MHz).

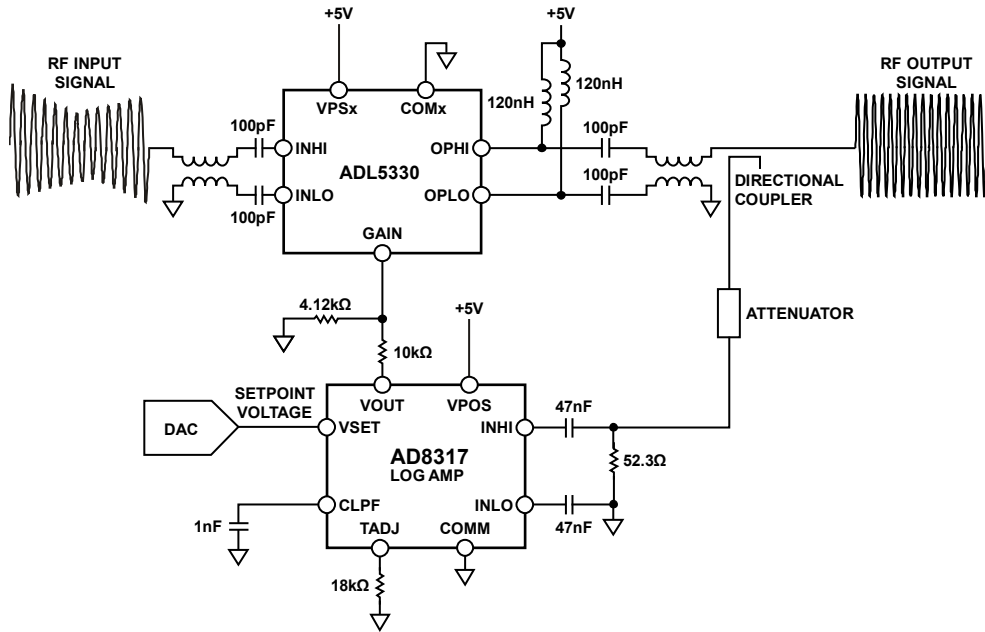


Figure 30. AD8317 Operating in Controller Mode to Provide Automatic Gain Control Functionality in Combination with the ADL5330

Figure 31 shows the transfer function of the output power vs. the setpoint voltage over temperature for a 900 MHz sine wave with an input power of  $-1.5$  dBm. Note that the power control of the AD8317 has a negative sense. Decreasing  $V_{SET}$ , which corresponds to demanding a higher signal from the ADL5330, increases gain.

The AGC loop is capable of controlling signals just under the full 60 dB gain control range of the ADL5330. The performance over temperature is most accurate over the highest power range, where it is generally most critical. Across the top 40 dB range of output power, the linear conformance error is well within  $\pm 0.5$  dB over temperature.

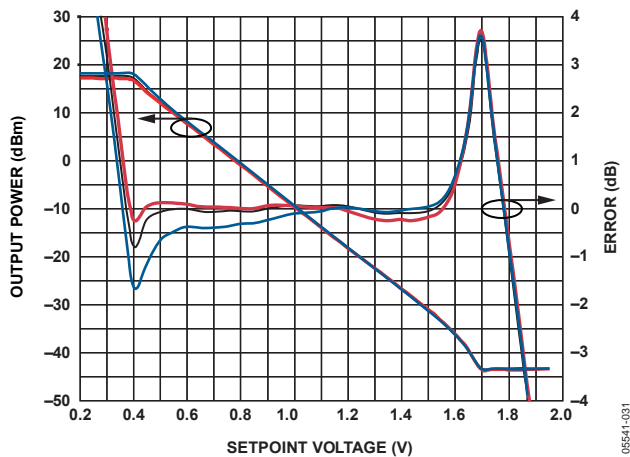


Figure 31. ADL5330 Output Power vs. AD8317 Setpoint Voltage,  $P_{IN} = -1.5$  dBm

For the AGC loop to remain in equilibrium, the AD8317 must track the envelope of the ADL5330 output signal and provide the necessary voltage levels to the ADL5330 gain control input. Figure 32 shows an oscilloscope screenshot of the AGC loop depicted in Figure 30. A 100 MHz sine wave with 50% AM modulation is applied to the ADL5330. The output signal from the VGA is a constant envelope sine wave with amplitude corresponding to a setpoint voltage at the AD8317 of 1.5 V. Also shown is the gain control response of the AD8317 to the changing input envelope.

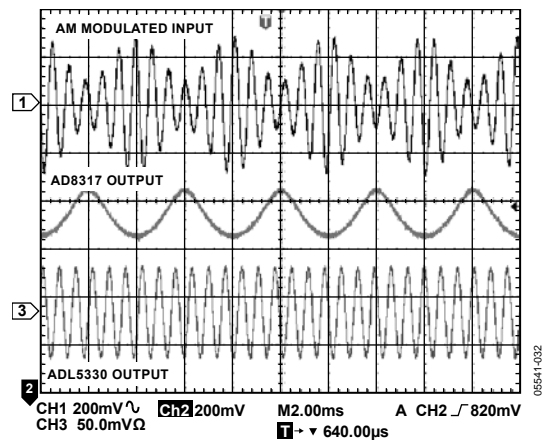


Figure 32. Oscilloscope Screenshot Showing an AM Modulated Input Signal and the Response from the AD8317



Figure 33 shows the response of the AGC RF output to a pulse on VSET. As V<sub>SET</sub> decreases from 1.7 V to 0.4 V, the AGC loop responds with an RF burst. In this configuration, the input signal to the ADL5330 is a 1 GHz sine wave at a power level of -15 dBm.

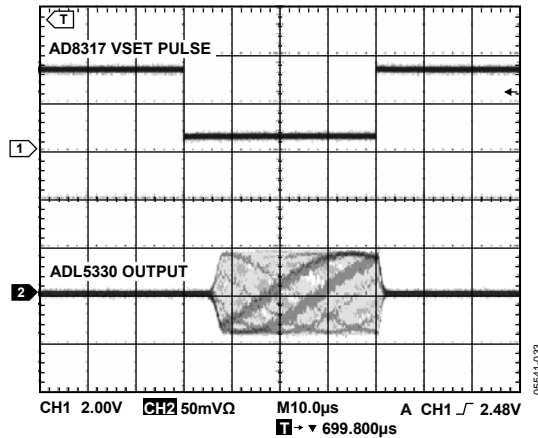


Figure 33. Oscilloscope Screenshot Showing the Response Time of the AGC Loop

Response time and the amount of signal integration are controlled by C<sub>FLT</sub>. This functionality is analogous to the feedback capacitor around an integrating amplifier. Although it is possible to use large capacitors for C<sub>FLT</sub>, in most applications, values under 1 nF provide sufficient filtering.

Calibration in controller mode is similar to the method used in measurement mode. A simple 2-point calibration can be done by applying two known V<sub>SET</sub> voltages or DAC codes and measuring the output power from the VGA. Slope and intercept can then be calculated by:

$$\text{Slope} = (V_{SET1} - V_{SET2}) / (P_{OUT1} - P_{OUT2}) \quad (9)$$

$$\text{Intercept} = P_{OUT1} - V_{SET1} / \text{Slope} \quad (10)$$

$$V_{SETX} = \text{Slope} \times (P_{OUTX} - \text{Intercept}) \quad (11)$$

More information on the use of the ADL5330 in AGC applications can be found in the ADL5330 data sheet.

### OUTPUT FILTERING

For applications in which maximum video bandwidth and, consequently, fast rise time are desired, it is essential that the CLPF pin be left unconnected and free of any stray capacitance.

The nominal output video bandwidth of 50 MHz can be reduced by connecting a ground-referenced capacitor (C<sub>FLT</sub>) to the CLPF pin, as shown in Figure 34. This is generally done to reduce output ripple (at twice the input frequency for a symmetric input waveform such as sinusoidal signals).

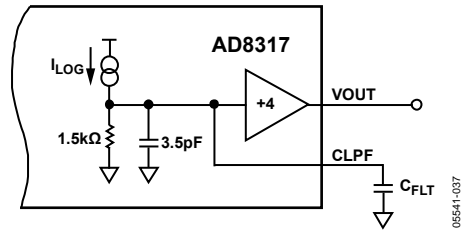


Figure 34. Lowering the Postdemodulation Bandwidth

C<sub>FLT</sub> is selected by

$$C_{FLT} = \frac{1}{(2\pi \times 1.5 \text{ k}\Omega \times \text{Video Bandwidth})} - 3.5 \text{ pF} \quad (12)$$

The video bandwidth must typically be set to a frequency equal to about one-tenth the minimum input frequency. This ensures that the output ripple of the demodulated log output, which is at twice the input frequency, is well filtered.

In many log amp applications, it may be necessary to lower the corner frequency of the postdemodulation filter to achieve low output ripple while maintaining a rapid response time to changes in signal level. An example of a 4-pole active filter is shown in the AD8307 data sheet.

### OPERATION BEYOND 8 GHz

The AD8317 is specified for operation up to 8 GHz, but it provides useful measurement accuracy over a reduced dynamic range of up to 10 GHz. Figure 35 shows the performance of the AD8317 over temperature at 10 GHz when the device is configured as shown in Figure 22. Dynamic range is reduced at this frequency, but the AD8317 does provide 30 dB of measurement range within ±3 dB of linearity error.

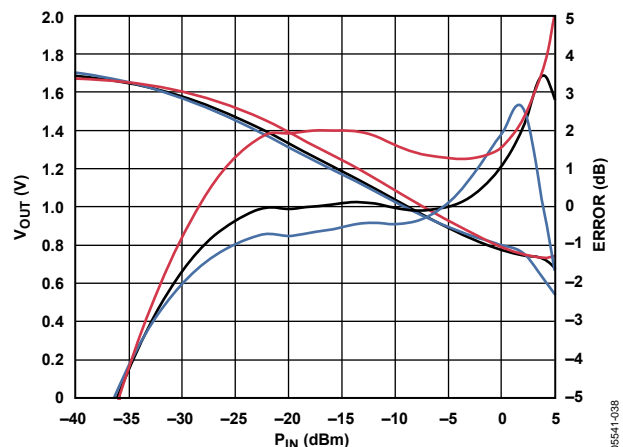


Figure 35. V<sub>OUT</sub> and Log Conformance vs. Input Amplitude at 10.0 GHz, Multiple Devices, R<sub>TADJ</sub> = Open, C<sub>LPF</sub> = 1000 pF

Implementing an impedance match for frequencies beyond 8 GHz can improve the sensitivity of the AD8317 and measurement range.

Operation beyond 10 GHz is possible, but part-to-part variation, most notably in the intercept, becomes significant.

## EVALUATION BOARD

Table 5. Evaluation Board (Rev. A) Configuration Options

Component	Function	Default Conditions
VPOS, GND	Supply and Ground Connections.	Not applicable
R1, C1, C2	Input Interface. The 52.3 Ω resistor in Position R1 combines with the internal input impedance of the AD8317 to give a broadband input impedance of about 50 Ω. C1 and C2 are dc-blocking capacitors. A reactive impedance match can be implemented by replacing R1 with an inductor and C1 and C2 with appropriately valued capacitors.	R1 = 52.3 Ω (Size 0402) C1 = 47 nF (Size 0402) C2 = 47 nF (Size 0402)
R5, R7	Temperature Compensation Interface. The internal temperature compensation network is optimized for input signals up to 3.6 GHz when R7 is 10 kΩ. This circuit can be adjusted to optimize performance for other input frequencies by changing the value of the resistor in Position R7. See Table 4 for specific R <sub>TADJ</sub> resistor values.	R5 = 200 Ω (Size 0402) R7 = open (Size 0402)
R2, R3, R4, R6, RL, CL	Output Interface—Measurement Mode. In measurement mode, a portion of the output voltage is fed back to the VSET pin via R2. The magnitude of the slope of the VOUT output voltage response can be increased by reducing the portion of V <sub>OUT</sub> that is fed back to VSET. R6 can be used as a back-terminating resistor or as part of a single-pole, low-pass filter.	R2 = 0 Ω (Size 0402) R3 = open (Size 0402) R4 = open (Size 0402) R6 = 1 kΩ (Size 0402) RL = CL = open (Size 0402)
R2, R3	Output Interface—Controller Mode. In this mode, R2 must be open. In controller mode, the AD8317 can control the gain of an external component. A setpoint voltage is applied to Pin VSET, the value of which corresponds to the desired RF input signal level applied to the AD8317 RF input. A sample of the RF output signal from this variable gain component is selected, typically via a directional coupler, and applied to the AD8317 RF input. The voltage at the VOUT pin is applied to the gain control of the variable gain element. A control voltage is applied to the VSET pin. The magnitude of the control voltage can optionally be attenuated via the voltage divider comprising R2 and R3, or a capacitor can be installed in Position R3 to form a low-pass filter along with R2.	R2 = open (Size 0402) R3 = open (Size 0402)
C4, C5	Power Supply Decoupling. The nominal supply decoupling consists of a 100 pF filter capacitor placed physically close to the AD8317 and a 0.1 μF capacitor placed nearer to the power supply input pin.	C4 = 0.1 μF (Size 0603) C5 = 100 pF (Size 0402)
C3	Filter Capacitor. The low-pass corner frequency of the circuit that drives the VOUT pin can be lowered by placing a capacitor between CLPF and ground. Increasing this capacitor increases the overall rise/fall time of the AD8317 for pulsed input signals. See the Output Filtering section for more details.	C3 = 8.2 pF (Size 0402)

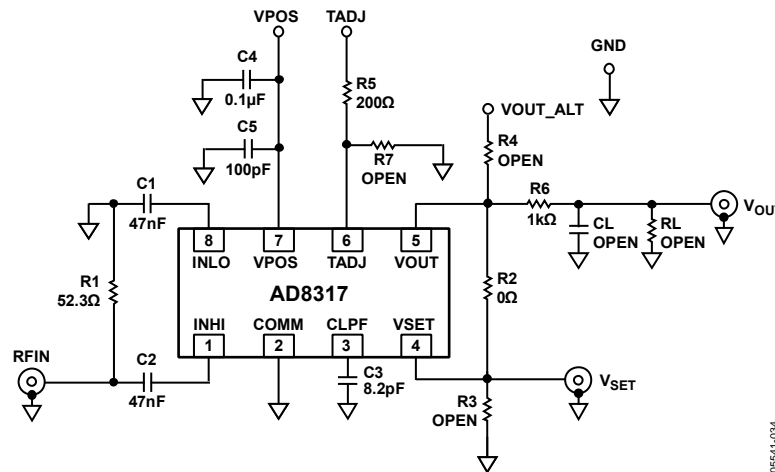
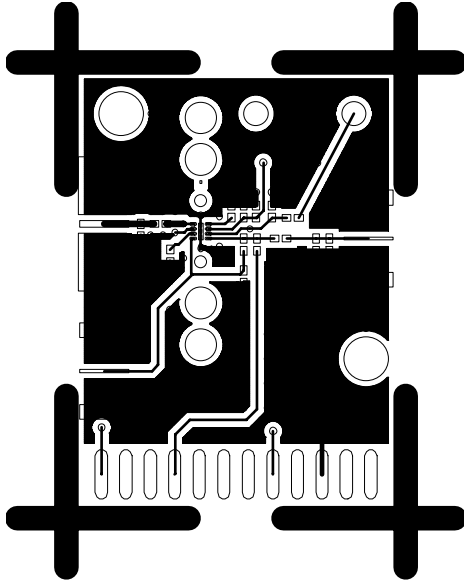


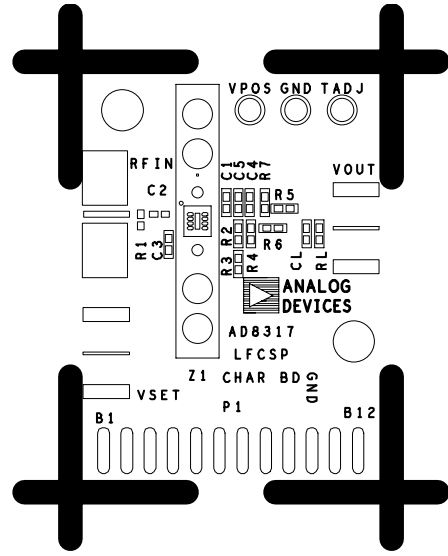
Figure 36. Evaluation Board Schematic





05541-036

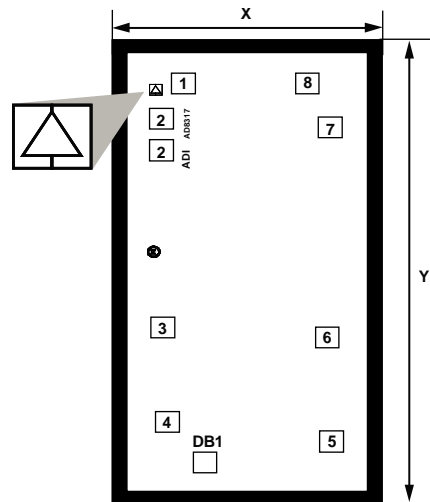
Figure 37. Component Side Layout



05541-036

Figure 38. Component Side Silkscreen

## DIE INFORMATION

**BOND PAD STATISTICS**

ALL MEASUREMENTS IN MICRONS.  
 MINIMUM PASSIVATION OPENING: 59 × 59 MIN PAD PITCH: 89

**DIE SIZE CALCULATION**  
ALL MEASUREMENTS IN MICRONS.

DIE X (WIDTH OF DIE IN X DIRECTION) = 670  
 DIE Y (WIDTH OF DIE IN Y DIRECTION) = 1325

DIE THICKNESS = 305 MICRONS

BALL BOND SHEAR STRENGTH SPECIFICATION: MINIMUM 15 GRAMS

05541-039

Figure 39. Die Outline Dimensions

Table 6. Die Pad Function Descriptions

Pin No.	Mnemonic	Description
1	INHI	RF Input. Nominal input range of $-50$ dBm to $0$ dBm, referenced to $50 \Omega$ ; ac-coupled RF input.
2, 2	COMM	Device Common. Connect both pads to a low impedance ground plane.
3	CLPF	Loop Filter Capacitor. In measurement mode, this capacitor sets the pulse response time and video bandwidth. In controller mode, the capacitance on this node sets the response time of the error amplifier/integrator.
4	VSET	Setpoint Control Input for Controller Mode or Feedback Input for Measurement Mode.
5	VOUT	Measurement and Controller Output. In measurement mode, VOUT provides a decreasing linear-in dB representation of the RF input signal amplitude. In controller mode, VOUT is used to control the gain of a VGA or VVA with a positive gain sense (increasing voltage increases gain).
6	TADJ	Temperature Compensation Adjustment. Frequency-dependent temperature compensation is set by connecting a ground-referenced resistor to this pin.
7	VPOS	Positive Supply Voltage: $3.0$ V to $5.5$ V.
8	INLO	RF Common for INHI. AC-coupled RF common.
DB1	COMM	Device Common. Connect to a low impedance ground plane.

# OUTLINE DIMENSIONS

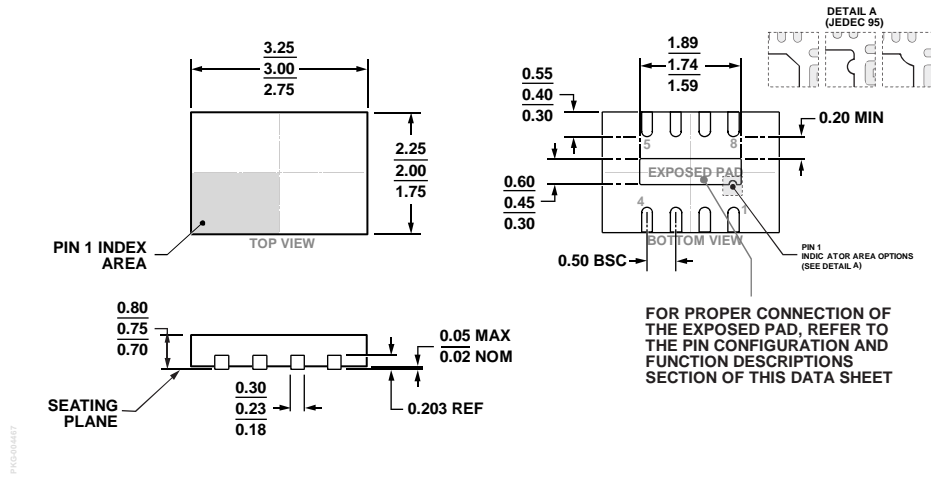


Figure 40. 8-Lead Lead Frame Chip Scale Package [LFCSP]  
 2 mm × 3 mm Body and 0.75 mm Package Height  
 (CP-8-23)  
 Dimensions shown in millimeters

## ORDERING GUIDE

Model <sup>1</sup>	Temperature Range	Package Description	Package Option	Branding
AD8317ACPZ-R7	-40°C to +85°C	8-Lead LFCSP, 7" Tape and Reel	CP-8-23	Q1
AD8317ACPZ-R2	-40°C to +85°C	8-Lead LFCSP, 7" Tape and Reel	CP-8-23	Q1
AD8317ACPZ-WP	-40°C to +85°C	8-Lead LFCSP, Waffle Pack	CP-8-23	Q1
AD8317ACHIPS	-40°C to +85°C	Die		
AD8317-EVALZ		Evaluation Board		

<sup>1</sup> Z = RoHS Compliant Part.